



README Document for

Nimbus 1

High Resolution Infrared Radiometer

(HRIR) Level 1 Data:

HRIRN1L1

HRIRN1IM

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## Revision History

Revision date	Changes	Author
08/04/2011	Initial version	Emily Zamkoff
03/29/2013	Original document only described image product. This version describes both data and the image products..	James Johnson

## Table of Contents

1. Introduction .....	4
1.1 Brief Background .....	4
1.2 Brief Background on Instruments .....	4
1.3 Brief Background on Algorithms .....	5
2. Data Organization .....	6
2.1 Granularity .....	6
2.2 File Naming Convention .....	6
2.3 File Format (TAP) .....	7
2.3.1 TAP Bytes .....	7
2.3.2 TAP Headers .....	8
2.3.3 Nimbus HRIR Word .....	8
2.4 Data Structure inside File .....	9
2.5 Key Metadata Fields .....	10
3. Data Contents .....	11
4. Data Services .....	11
5. Data Organization .....	12
5.1 Geolocation .....	12
6. More Information .....	13
6.1 Web Resources .....	13
6.2 Point of Contact .....	13
6.3 References .....	13
7. More Information .....	14
7.1 Example of a C Routine to Read TAP Headers .....	14
7.2 Example on How to Read a 36-bit Binary Word using C .....	14
7.3 Description of all Metadata Fields .....	16
7.4 Description of Orbit Documentation Record .....	17
7.5 Description of Data Documentation Record .....	19
7.6 Description of a Swath Data Record .....	20
7.7 File Format (TAP) .....	22
7.7.1 Definition of Flags Describing each HRIR Swath .....	22
7.7.2 Definition of Flags for Individual Measurements .....	22
7.8 Quality Assurance Procedures .....	23
7.8.1 Data Producer QA .....	23
7.8.2 Physical QA .....	23
7.8.3 Science QA .....	24
7.9 Image Files .....	24
7.10 Acronyms .....	25

## Illustration Index

Figure 1: Nimbus HRIR optical system.....	5
Figure 2: Data restoration process .....	8
Figure 3: Nimbus HRIR data structure .....	10
Figure 4: Nimbus anchor points.....	12

## Table Index

Table 1: XML Metadata Fields.....	16
Table 2: Orbit Documentation Record.....	18
Table 3: Data Documentation Record.....	19
Table 4: Swath Data Record .....	20
Table 5: Swath Flag Definition.....	22
Table 6: Individual Measurement Flags .....	22

# README document for Nimbus 1 HRIR

## 1. Introduction

### 1.1 Brief Background

This document applies to the Nimbus 1 High Resolution Infrared Radiometer (HRIR) Level-1 data. The HRIR instrument maps the Earth's nighttime cloud cover and measures the temperatures of cloud tops and surface features. The HRIR experiment incorporates a single channel scanning radiometer and operates in the 3.5 – 4.1 micron window region.

The Nimbus 1 satellite was successfully launched on August 28, 1964 at 08:52 UTC and included the following three instruments:

- An Advanced Vidicon Camera System (AVCS) to provide daytime cloud mapping.
- An Automatic Picture Transmission (APT) System to provide daytime slow-scan television pictures of cloud cover conditions.
- A High Resolution Infrared Radiometer (HRIR) to provide nighttime surface and cloud top temperatures, and cloud mapping (3.5 – 4.1 microns).

The orbit of the satellite can be characterized by the following:

- elliptical orbit of 423 km at perigee and 932.7 km at apogee.
- inclination of 98.66 degrees
- period of an orbit is about 98.31 minutes
- orbits cross the equator at 26 degrees of longitude separation
- retrograde near-polar

The satellite failed to reach a planned circular sun-synchronous orbit due to a shortened burn of second stage of the launch vehicle. The Nimbus 1 HRIR data are available from 28 August 1964 (day of year 241) through 22 September 1964 (day of year 266).

### 1.2 Brief Background on Instruments

The High Resolution Scanning Radiometer (HRIR) is a single-channel dual band-pass scanning radiometer using a PbSe photoconductive detector cell radiatively cooled to -77 deg C. Nighttime operation is in the 3.5 – 4.1 micron infrared region, to complement the AVCS daytime measurements. HRIR provides measurements of blackbody temperatures between 210K and 330K with a noise equivalent of ~1 degree C for a 260K background. The scanning is coincident with spacecraft velocity vector resulting in no yaw error. The scan mirror is inclined to 45 degrees to the axis of rotation (scans perpendicular to flight path) and the scan rate operation is 48 revolutions per minute. The HRIR instrument ran

successfully until September 22, 1964 when the Nimbus-1 spacecraft's solar paddles became locked in position, resulting in inadequate electrical power to continue operations.

The HRIR optical system is illustrated in Figure 1

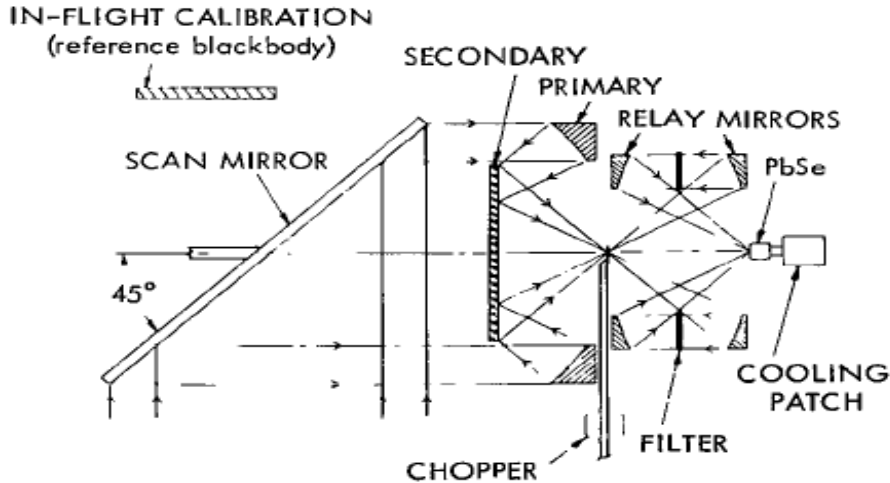


Figure 1: Nimbus HRIR optical system

### 1.3 Brief Background on Algorithms

The Nimbus 1 HRIR data was generated from the spacecraft telemetry, attitude data, orbital data, digitized radiation data, and the Nimbus radiometer calibration package. The data were created on IBM computers using a 36-bit architecture. Further information can be found in the Nimbus I User's Guide Volume 2 (HRIR Data Catalog and User's Manual)1.

## 2. Data Organization

### 2.1 Granularity

The Nimbus 1 HRIR data were originally archived on 7-track tapes. The data were stored in 36-bit IBM binary format. A Canadian company (JBI) was contracted to restore to disks all of the Nimbus 1 HRIR tapes. The content of each tape was written using a proprietary binary format that allowed “bad” bytes or records to be flagged. Since tapes may contain several files and in some cases several orbits, the content of each file on a tape was retrieved and stored in a separate file using the same format.

The Nimbus 1 HRIR tapes were archived at the Washington National Records Center. The tape recovery process involved using specially developed tape drives, bit detection and processing techniques to read the 800 bpi, 7-track tapes and store the recovered data in TAP (tape emulation format). Nimbus 1 HRIR data cover about 1 month of observations, and all recoverable orbit files (123 out of 124) from the 7-track tapes were successfully restored.

Because a tape may contain multiple files, and in some cases multiple orbits, each tape was read and the content of each file stored on a separate file on disk. The overall TAP format and data on tape was preserved. The TAP files were archived and ingested at the Goddard Earth Sciences Data and Information Services Center (GES DISC) and are available for users to download.

There are cases where a file is retrieved from a backup tape. Some times the backup file will have the same time stamp and orbit number as a file extracted from the primary tape. If the data values are not identical in the two files, the backup file will be retained. However, its name is appended with “-dup” after the version number to indicate it is a duplicate file.

### 2.2 File Naming Convention

The Nimbus 1 HRIR level 2 data are named according to the following convention:

*<Satellite>-<Instrument>\_<StartTime>\_o<Orbit>\_v<Version>.<Ext>*

where:

<i>Satellite</i>	is always Nimbus1
<i>Instrument</i>	is always HRIR
<i>Starttime</i>	is the starting time when the data was collected from the satellite using the format YYYYmMMDDtHHNNSS with

## README document for Nimbus 1 HRIR

*YYYY*: 4 digit calendar year (e.g. 1964)

*m* is a separator between year and month/day

*MM*: 2 digit month of year (e.g. 09 for September)

*DD*: 2 digit day of the month (e.g. 13)

*t* is a separator between date and time

*HH*: 2 digit hour of the day (e.g. 17)

*NN*: 2 digit minutes of the hour (e.g. 38)

*SS*: 2 digit seconds (e.g. 35)

*Orbit* is the 5 digit orbit number preceded by lowercase o (e.g. o00241)

*Version* is a 3 digit data collection number (e.g. 001)

*Ext* is the file extension type and always TAP

example: Nimbus1-HRIR\_1964m0913t173835\_o00241\_v001.TAP

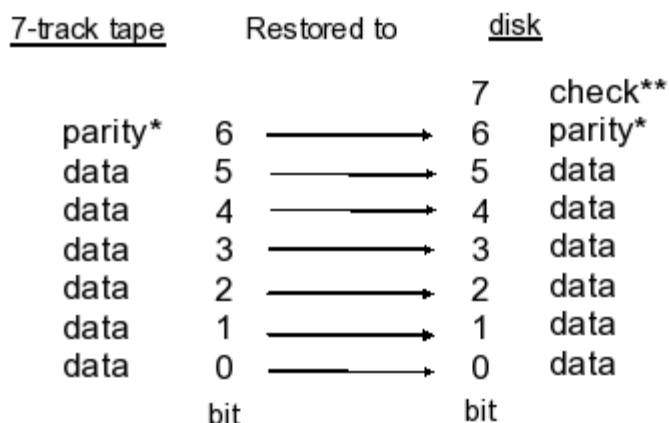
(note duplicate files are indicated by “-dup” following version number)

### 2.3 File Format (TAP)

#### 2.3.1 TAP Bytes

Each byte restored from a 7-track tape is stored in a byte as described in the following Figure 2. The 7<sup>th</sup> bit is flagged to 1 when a byte was not restored correctly; otherwise it is set to 0. The 6<sup>th</sup> bit is the tape parity bit as stored on tape.





**Figure 2: Data restoration process**

### 2.3.2 TAP Headers

TAP headers are interleaved between the Nimbus 1 HRIR data records to indicate the length of the following and preceding data records. A TAP header is a 4 byte record which follows the following convention.

- A number greater than zero indicates the length of a record
- A negative number indicates that a record has bytes that could not be restored from tapes and filled with zeros. The length of a record is obtained by taking the absolute value.
- a zero indicates the start of a file
- Two consecutive TAP headers with zero values are used to specify the end of a file.
- A data record is preceded by a header and followed by a header listing the length of the data record

An example of how to read a TAP header is illustrated in appendix 7.1

### 2.3.3 Nimbus HRIR Word

The basic unit of the Nimbus HRIR data is a word which is a 36-bit IBM binary word. This means that in order to extract a 36-bit word from the restored files, six bytes (8-bits)

## README document for Nimbus 1 HRIR

must be read, the 6<sup>th</sup> and 7<sup>th</sup> bit removed from each byte, and the remaining bits of each byte combined.

To preserve space while maintaining a good resolution, a scaling technique was used when the data was originally created and stored on 7-track tapes. The idea was to multiply a number by a factor before storing the value to tape. Nimbus data can be converted back to the initial value by dividing the stored value on tape by  $2^{(35-B)}$ , where B is the scaling factor listed on the Nimbus data record format tables.

A word of 36 bits with a scaling factor of B is converted by using the relation:

$$\text{value} = (\text{integer value of 36 bits}) / (2^{(35-B)})$$

When a word is divided in two  $\frac{1}{2}$  Words (WordD and WordA), the actual values are converted by using the relation:

A wordD of 18bits with a scaling factor of B is converted in real by using the relation:

$$\text{value} = (\text{integer value of 18 bits}) / (2^{(17-B)})$$

A wordA of 18bits with a scaling factor of B is converted in real by using the relation:

$$\text{value} = (\text{integer value of 18 bits}) / (2^{(35-B)})$$

The scaling factor is mentioned and used in tables describing the Nimbus HRIR records.

An example on how to read a Nimbus 36-bit word is illustrated in Appendix 7.2

### 2.4 Data Structure inside File

Two TAP 4 byte headers are stored before and after each Nimbus HRIR records. The first Nimbus HRIR record is an orbit data document record (102 bytes) followed by multiple data records. A Nimbus data record is composed of a Data record documentation followed by several swath data records. The length of a data record (L) in words can be computed using the relation.

$$L = (\text{swaths per records}) \times (\text{words per swath}) + (\text{number of nadir angles}) + 7$$

The overall structure of the Nimbus 1 files is depicted in Figure 3

## README document for Nimbus 1 HRIR

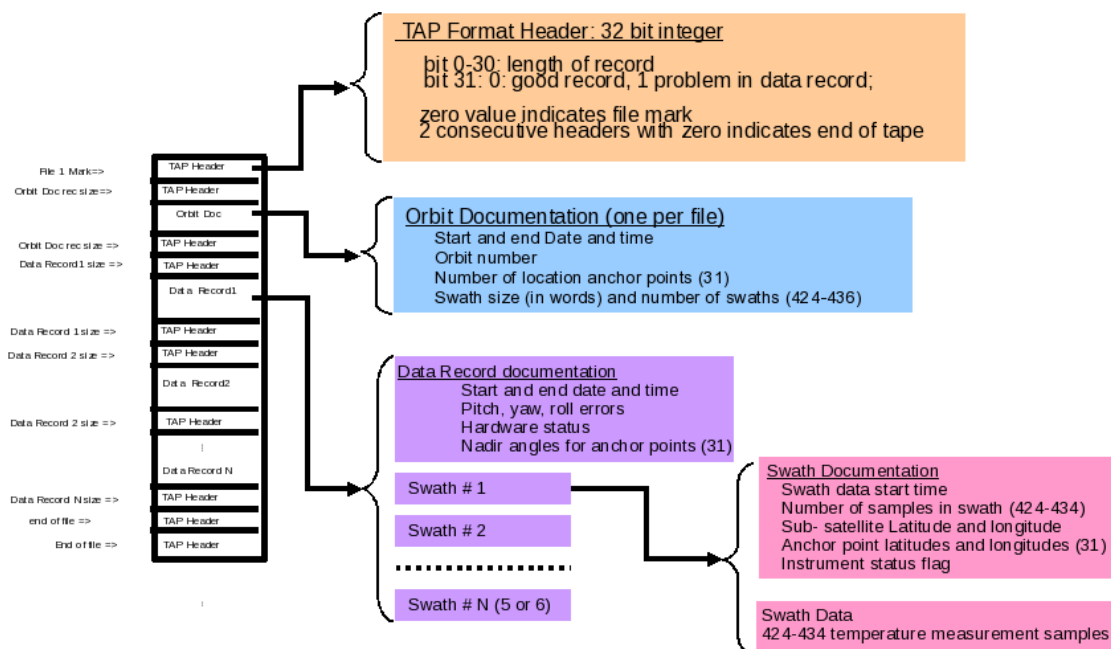


Figure 3: Nimbus HRIR data structure

### 2.5 Key Metadata Fields

These are most likely to be used by users:

#### Temporal

- Start Date / Time
- End Date/ Time

#### Geolocation

- Latitude
- Longitude

## README document for Nimbus 1 HRIR

### 3. Data Contents

Described below are all the parameters associated with the Nimbus HRIR data files.

Table 2 describes in details all the parameters associated with an orbit. There is one orbit documentation record per file.

Table 3 describes in details all fields in a data record documentation. There is one data documentation record per data record

Table 4 describes in details all fields in a swath data record. There are multiple swath data records in a single data record.

### 4. Data Services

Nimbus 1 HRIR products can be searched and ordered by using Reverb, ECHO's next generation metadata and services discovery tool at:

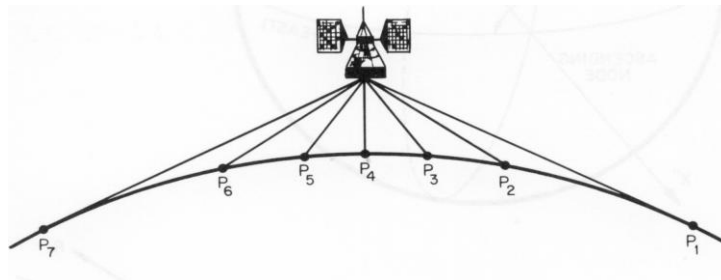
<http://reverb.echo.nasa.gov/>

## 5. Data Organization

### 5.1 Geolocation

The Nimbus pointing accuracy is better than 1 degree in pitch and roll with 1 degree pointing error that corresponds to a sub-satellite geo-location error of 20 km. The HRIR radiometer scans the Earth in a clockwise direction from right to left. Each scan is defined by a family of mirror nadir angles. For each mirror angle, the latitude and longitude of the corresponding point on the Earth's surface is recorded. The position of individual samples between two anchor points is determined by interpolation.

The latitude and longitude of the corresponding point on the Earth's surface are used as references in computation of positions for each sample. There is still no information available describing how many anchor points were used for a swath. Using landmarks and Nimbus II data (e.g. Lake Michigan) it seems that 11 anchor points centered around the subsatellite points were used, instead of the 31 points. This issue is still being investigated.



**Figure 4: Nimbus anchor points**

## README document for Nimbus 1 HRIR

### 6. More Information

#### 6.1 Web Resources

##### **NASA/GSFC**

Nimbus Documentation:

<http://disc.sci.gsfc.nasa.gov/nimbus/documentation/>

#### 6.2 Point of Contact

URL: <http://disc.gsfc.nasa.gov/>

Name: GES DISC Help Desk

E-mail: [help-disc@listserv.gsfc.nasa.gov](mailto:help-disc@listserv.gsfc.nasa.gov)

Phone: 301-614-5224

Fax: 301-614-5268

Address:

Goddard Earth Sciences Data and Information Services Center

Code 610.2

NASA Goddard Space Flight Center

Greenbelt, MD 20771, USA

#### 6.3 References

- Nimbus I User's Guide Volume 1 (Film Data), January 1965
- Nimbus I User's Guide Volume 2 (HRIR Data Catalog and User's Manual)

## 7. More Information

### 7.1 Example of a C Routine to Read TAP Headers

Following is an example on how to extract the record length from the TAP headers

```
int ReadHeader(ifd)      /* read header */
int ifd;

/* This function reads a TAP header (4 bytes) and return
   the size in bytes of the next record to read
   input
       ifd: file reference
   output
       reclen: size of the next record in bytes
*/

{
unsigned char    bytebuf[200];
int    j, size, value,reclen,signbit;

    size = read( ifd, bytebuf, 4) ;      /* read header */

    value = 0;
    for (j=0 ; j<=3 ; j++ )
        {
            value = value << 8;          /* shift left by 8 bits */
            value = value | bytebuf[j];
        }
    reclen = value;
    return reclen;
}
```

### 7.2 Example on How to Read a 36-bit Binary Word using C

Below is an example of a C routine to extract the 36 bit word (out of 6 unsigned bytes), remove the most significant bits of each byte and store the content into a long long interger.

## README document for Nimbus 1 HRIR

```
long long GetWord (initval,len)
unsigned char  initval[];      /* buffer containing the binary data */
int len;                      /* number of bytes */

/*  this function removes the 2 most significant bits of each byte
    and concatenates the "len" bytes (with the 2 bits removed)
    into an integer
input
    initval array containing the bytes
    len      number of bytes to clean and concatenate
output
    value    integer containing the bytes cleaned and concatenated
*/
{
int j,pos;
unsigned char  byteclean;
long long value,signbit,res, signval;

    value = 0;
    pos=0;
    signval = 1;
    for (j=0 ; j<len ; j++ )
    {
        if ( j == 0 )
        {
            signbit = initval[pos] & 0x20;    /* get sign bit */
            if ( signbit == 32 )
            {
                value = value << 5;    /* shift left by 5 bits
                                         to remove sign bit */
                signval = -1;
                byteclean = initval[pos] & 0x1f;
                value = value | byteclean;
            }
            else
            {
                value = value << 6;    /* shift left by 6 bits
                                         to remove sign bit */
                byteclean = initval[pos] & 077; /* remove the 2
                                         most significant bits */
                value = value | byteclean;
            }
        }
        else
        {
            value = value << 6;        /* shift left by 6 bits */
            byteclean = initval[pos] & 077; /* remove the 2 most
                                         significant bits */
            value = value | byteclean;
        }
        pos++;
    }

    value = value*signval;
    return value;
}
```



### 7.3 Description of all Metadata Fields

Following is a list of the XML metadata fields and a brief description of the HRIR data.

**Table 1: XML Metadata Fields**

<b>field</b>	<b>Description</b>	<b>value</b>
LongName	Long name of the product	Nimbus 3 Meteorological Radiation Tape - HRIR (NMRT-HRIR)
ShortName	Short name of the product	HRIRN1L1
VersionID	Version ID of the ingested data product, not the processing version.	Example: 001
GranuleID	Granule ID (same as the name of the file).	Example: Nimbus1-HRIR_1964m0913t173835_o00241_v001.TAP
Format	File Format (see section on TAP for a full description).	TAP
CheckSumType	Type of check sum	CRC32
CheckSumValue	Value of the check sum using cksum command	Example: 3796183461
SizeBytes DataGranule	Total size of the data granule in bytes	Example: 3509896
InsertDateTime	Date and time when the granule was inserted into the archive. The date is YYYY-MM-DD and the time is in hh-mm-ss format	Example: 2013-01-16 16:46:57
RangeBeginning Date	Begin date when the data was collected. The date is in YYYY-MM-DD format	Example: 1964-09-13
RangeBeginning Time	Begin time of date when the data was collected. The time is in hh-mm-ss format	Example: 17:38:35
RangeEnding Date	End date when the data was collected. The date is in YYYY-MM-DD format	Example: 1964-09-13
RangeEnding Time	End time of date when the data was collected. The time	Example: 18:18:05

## README document for Nimbus 1 HRIR

<b>field</b>	<b>Description</b>	<b>value</b>
	is in hh-mm-ss format	
Platform ShortName	Acronym or short name of the satellite or platform.	Nimbus1
Instrument ShortName	Acronym or short name of the instrument.	HRIR
SensorShortName	Name of the sensor	HRIR
Gpolygon PointLatitude	Latitudes of the polygons that represent the satellite coverage. Rectangles have been selected in this case. Each point of a rectangle is identified by its latitude and longitude	Example:  -80.000000 -90.000000 -90.000000 -80.000000
Gpolygon PointLongitude	Longitudes of the polygons that represent the satellite coverage. Rectangles have been selected in this case. Each point of a rectangle is identified by its latitude and longitude	Example:  180.000000 180.000000 -180.000000 -180.000000
Orbit	Satellite orbit number. There is one orbit per file. A given orbit may have several files (partial orbits or data collected from different stations)	Example: 241
Average_Elevation	Average elevation in km of the satellite during an orbit	Example: 703.578
Station_Code	DAF Station identification code	Example: 2
Elapsed_Min_Time	Duration in minutes of data collected during an orbit	Example: 39

### 7.4 Description of Orbit Documentation Record

This record is unique for each file and provides information on the starting and end Date/Time for a file, size and number of swaths, orbit number, and the number of anchor points used to identify the geo-location of the data.

# README document for Nimbus 1 HRIR

**Table 2: Orbit Documentation Record**

Word No.	Quantity	Units	Scaling	Remarks
1	Dref	-----	B=35	number of days between 0 hour on 9/1/57 and zero hour on the day of launch)
2	Date	MMDDYY	B=35	Date of interrogation for this orbit (MMDDYY 2/5/64 is (020504) in octol. Date of interrogation seems to be the processing date
3	Nimbus Day	-----	B=35	Start day of the year (1969) for this file (orbit)
4	Hour	hh	B=35	Start hour for this file(orbit)
5	Minute	mm	B=35	Start minute for this file(orbit)
6	Second	ss	B=35	Start seconds for this file(orbit)
7	Nimbus Day	-----	B=35	End day of the year (1969) for this orbit
8	Hour	hh	B=35	End hour for this orbit
9	Minute	mm	B=35	End minute for this orbit
10	Second	ss	B=35	End seconds for this orbit
11	Mirror Rotation	deg/sec	B=26	Rotation rate of radiometer mirror
12	Sampling Frequency	samples/sec	B=35	Digital sampling frequency per second of vehicle time
13	Orbit Number	-----	B=35	Orbit Number
14	Station Code	-----	B=35	Data Acquisition Facility (DAF) Station identification
15	Swath Block size	-----	B=35	Number of 36-bit words per swath
16	Swaths/records	-----	B=35	Number of swath per record
17	Number of locator points	-----	B=35	Number of anchor points per swath for which latitudes and longitudes are computed

## 7.5 Description of Data Documentation Record

The data documentation record provides information describing the subsequent swath data records.

**Table 3: Data Documentation Record**

<b>Word No.</b>	<b>Quantity</b>	<b>Units</b>	<b>Scaling</b>	<b>Remarks</b>
1D	Nimbus Day	-----	B=17	Start Day of the year for this data record
1A	Hour	hh	B=35	Start hour for this data record
2D	Minute	mm	B=17	Start minute for this data record
2A	Second	ss	B=35	Start seconds for this data record
3D	Roll Error	degrees	B=14	Roll error at start date/time (word 1 and 2) for this record
3A	Pitch Error	degrees	B=32	Pitch error at start date/time (word 1 and 2) for this record
4D	Yaw Error	degrees	B=14	Yaw error at start date/time (word 1 and 2) for this record
4A	Height	km	B=35	Height of the spacecraft at start date/time (word 1 and 2) for this record
5D	Detector Cell Temperature	degrees K	B=17	Measured temperature of detector cell at start date/time (word 1 and 2) for this record
5A	Electronics Temperature	degrees K	B=35	Measured temperature of electronics at start date/time (word 1 and 2) for this record
6D	24V Supply	Volts	B=14	Measured voltage at start date/time (word 1 and 2) for this record
6A	20 V Supply	Volts	B=32	Measured voltage at start date/time (word 1 and 2) for this record
7D	Reference Temperature A	degrees K	B=17	Measured temperature of housing at start date/time

# README document for Nimbus 1 HRIR

Word No.	Quantity	Units	Scaling	Remarks
				(word 1 and 2) for this record
7A	Reference Temperature B	degrees K	B=35	Measured temperature of housing at start date/time (word 1 and 2) for this record
8	Nadir Angle	Degrees	B=29	Nadir angle corresponding to the first anchor point and measured in the plane of the radiometer
...				
...				
N	Nadir Angle	Degrees	B=29	Nadir angle corresponding to the last anchor point and measured in the plane of the radiometer

## 7.6 Description of a Swath Data Record

**Table 4: Swath Data Record**

Word No.	Quantity	Units	Scaling	Remarks
(N+1)D	Seconds	ss	B=8	Seconds elapsed since the start of the Date/time of this data record
(N+1)A	Data population	-----	B=35	Number of data points in this swath
(N+2)D	Latitude	degrees	B=11	Latitude of the subsatellite point for this swath
(N+2)A	Longitude	degrees	B=29	Longitude of the subsatellite point for this swath, positive westward 0 to 360
(N+3)	Flags	-----	-----	Reserved for flags describing this swath
(N+4)D	Latitude	degrees	B=11	Latitude of viewed point for the first anchor point
(N+4)A	Longitude	degrees	B=29	Longitude of viewed point for the first anchor point

README document for Nimbus 1 HRIR

Word No.	Quantity	Units	Scaling	Remarks
...				
...				
(N+3+M)D	Latitude	degrees	B=11	Latitude of viewed point for the Mth anchor point
(N+3+M)A	Longitude	degrees	B=29	Longitude of viewed point for the Mth anchor point
(N+4+M)D	HRIR Data	degrees	B=14	HRIR brightness temperature measurement
(N+4+M)A	HRIR Data	degrees	B=32	HRIR brightness temperature measurement
...				
...				
(N+K)D	HRIR Data	degrees	B=14	HRIR brightness temperature measurement
(N+K)A	HRIR Data	degrees	B=32	HRIR brightness temperature measurement

## 7.7 File Format (TAP)

### 7.7.1 Definition of Flags Describing each HRIR Swath

**Table 5: Swath Flag Definition**

Flag	Bit	Definition	Yes	No
1	35	Summary Flag. All checks defined by flags 2 through 12 are satisfactory. (Each flag is zero)	0	1
2	34	Consistency check between sampling rate, vehicle time, and ground time is satisfactory.	0	1
3	33	Vehicle time is satisfactory	0	1
4	32	Vehicle time has been inserted by flywheel	1	0
5	31	Vehicle time carrier is present	0	1
6	30	Vehicle time has skipped	1	0
7	29	Unassigned		
8	28	Sync pulse recognition was satisfactory	0	1
9	27	Dropout of data signal was detected	1	0
10	26	Unassigned		
11	25	unassigned		
12	24	Swath size satisfactory when compared with the theoretical swath size	0	1
13	23	unassigned		

### 7.7.2 Definition of Flags for Individual Measurements

**Table 6: Individual Measurement Flags**

Prefix	TAG	Definition	Yes	No
S	18	The particular measurement is below the Earth space threshold	1	0
1	19	unassigned		
2	20	unassigned		

## 7.8 Quality Assurance Procedures

### 7.8.1 Data Producer QA

The Data Producer's QA information can be found in the XML metadata file under the section ProducersQA. The information begins with the following:

```
Record No, Bytes, Bad bytes
0,filemark
1,84,0
2,filemark
3,102,0
4,11928,0
:
<n-1>,11928,0
<n>,filemark
```

On each line there are 3 comma separated numbers: the first is the record number, the second is the record length in bytes, and the third is the number of bad bytes. The first Record #0 is a filemark which separates different files. Record # 1 has 84 bytes - this is the BCD header length. If the number of bad bytes is 0, this indicates the header is good. If the number is non-zero, there are bad bytes in the header. Record # 2 marks the end of the BCD header, and the start of the next file record. Record #3 has 102 bytes - this is the data header length. If the number of bad bytes is 0, this means all bytes are good, if the number is non-zero, there are bad bytes in the header. Record #4 is 11928 bytes. This is the nominal data record length. If the number of bad bytes is 0, that indicates this data record is good, if the number is non-zero, there are bad bytes in the data record. From this point, all subsequent records are data records and should have a length of 11928 with no bad bytes. A final filemark will indicate the end of the file. Sometimes the data are split into different orbits or orbit section files, and this will be noted with another filemark

### 7.8.2 Physical QA

Each restored file was read and its corresponding orbit documentation was extracted and used to derive the file name and to create a XML metadata file.

For each file the number of "bad" bytes, parity errors, "bad" records was derived.

Plots of each swath were generated (with and without a world map).



### 7.8.3 Science QA

Nimbus I HRIR data were examined visually and validated using Nimbus1 HRIR documentation.

### 7.9 Image Files

The **HRIRN1IM** data product contains scanned negatives of photofacsimile 70mm film strips from the Nimbus-1 High-Resolution Infrared Radiometer. The images show orbital nighttime (3.5 to 4.1 microns) cloud cover and the Earth's surface measured as brightness temperatures. Each orbital swath picture is gridded with geographic coordinates and covers a distance approximately from the south pole to the north pole (day) and the north pole to the south pole (night). The images are saved as JPEG 2000 digital files. About 7 days of images are archived into a TAR file. The processing techniques used to produce the data set and a full description of the data are contained in section 2 of the "Nimbus I User's Guide Volume 1 (Film Data)."

These images can be used to supplement the radiance data files from the **HRIRN1L1** data product. The **HRIRN1IM** images can be ordered online using the Reverb tool (see section 4 above). The image files can be viewed with any application that supports the JPEG 2000 format

## 7.10 Acronyms

*DAF*: Data Acquisition Facility

*ECHO*: EOS Clearinghouse

*EOS*: Earth Observing System

*GES DISC*: Goddard Earth Sciences Data and Information Services Center

*GSFC*: Goddard Space Flight Center

*HRIR*: High Resolution Infrared Radiometer

*L2*: Level 2 Data

*NASA*: National Aeronautics and Space Administration

*Reverb*: ECHO's Next Generation Metadata and Service Discovery Tool

*QA*: Quality Assessment

*UT*: Universal Time